

# CS473 - Algorithms I



## Lecture 5 Quicksort

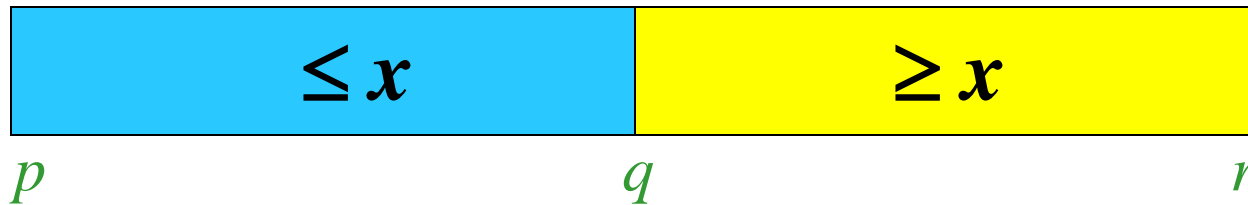
*View in slide-show mode*

# Quicksort

- One of the most-used algorithms in practice
- Proposed by C.A.R. Hoare in 1962.
- Divide-and-conquer algorithm
- In-place algorithm
  - The additional space needed is  $O(1)$
  - The sorted array is returned in the input array
  - *Reminder: Insertion-sort is also an in-place algorithm, but Merge-Sort is not in-place.*
- Very practical

# Quicksort

1. **Divide:** Partition the array into 2 subarrays such that elements in the lower part  $\leq$  elements in the higher part



2. **Conquer:** Recursively sort 2 subarrays
  3. **Combine:** Trivial (because in-place)
- Key: Linear-time ( $\Theta(n)$ ) partitioning algorithm

# Divide: Partition the array around a pivot element

1. Choose a **pivot** element  $x$
2. Rearrange the array such that:
  - Left subarray:** All elements  $\leq x$
  - Right subarray:** All elements  $\geq x$

Input: 

5	3	2	6	4	1	3	7
---	---	---	---	---	---	---	---

 e.g.  $x = 5$

After partitioning: 

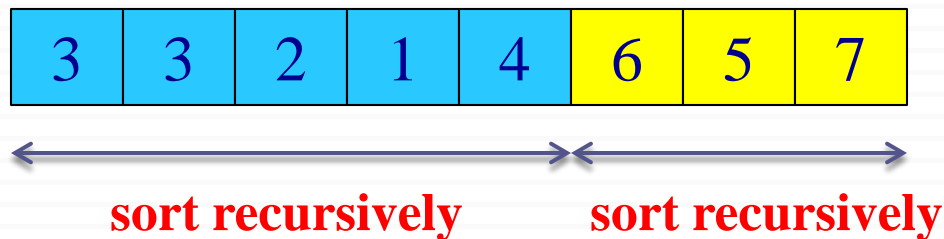
3	3	2	1	4	6	5	7
---	---	---	---	---	---	---	---

$\leq 5$                        $\geq 5$

# Conquer: Recursively Sort the Subarrays

Note: Everything in the left subarray  $\leq$  everything in the right subarray



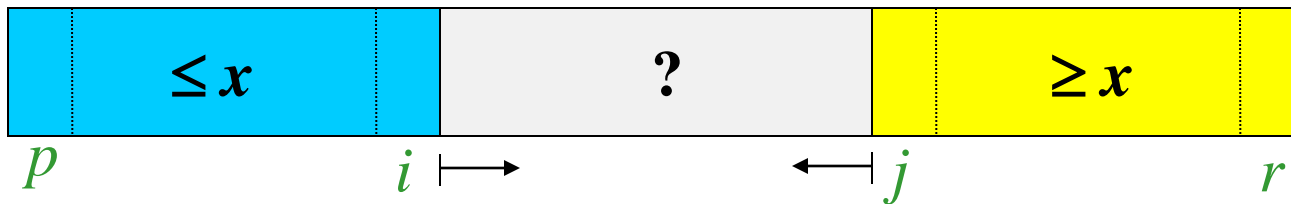
After conquer:



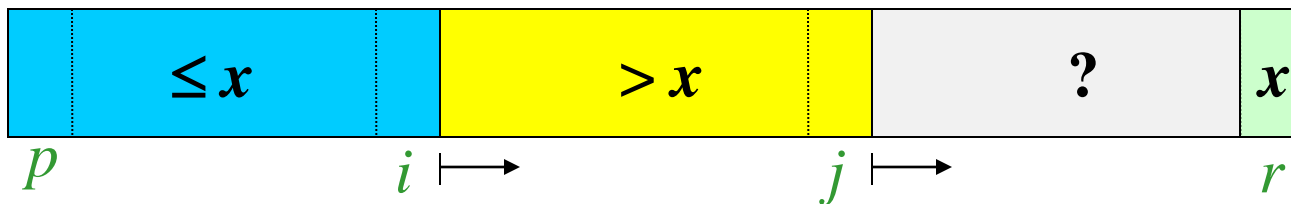
Note: Combine is trivial after conquer. Array already sorted.

# Two partitioning algorithms

1. **Hoare's algorithm:** Partitions around the first element of subarray ( $pivot = x = A[p]$ )



2. **Lomuto's algorithm:** Partitions around the last element of subarray ( $pivot = x = A[r]$ )



# Hoare's Partitioning Algorithm

1. **Choose** a pivot element:  $\text{pivot} = x = A[p]$

2. **Grow** two regions:

from **left to right**:  $A[p..i]$

from **right to left**:  $A[j..r]$

such that:

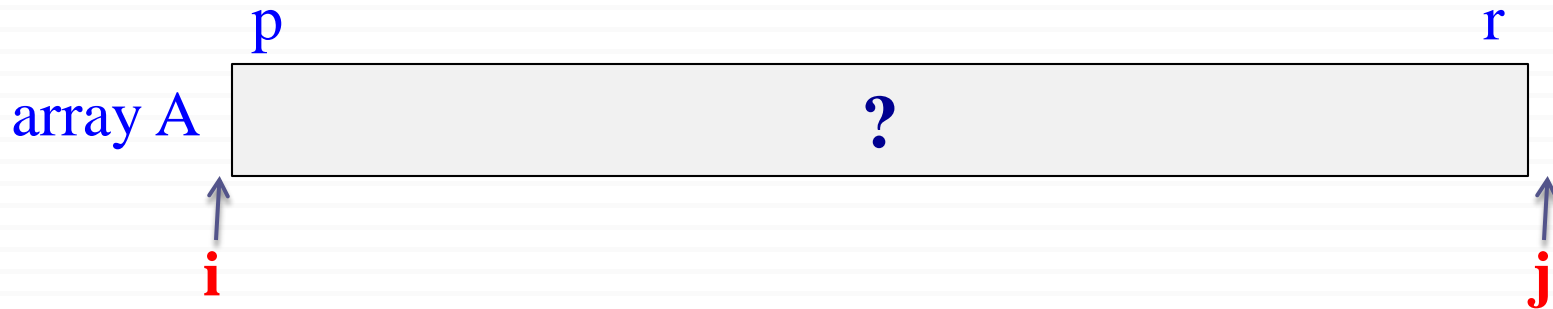
every element in  $A[p..i] \leq \text{pivot}$

every element in  $A[j..r] \geq \text{pivot}$



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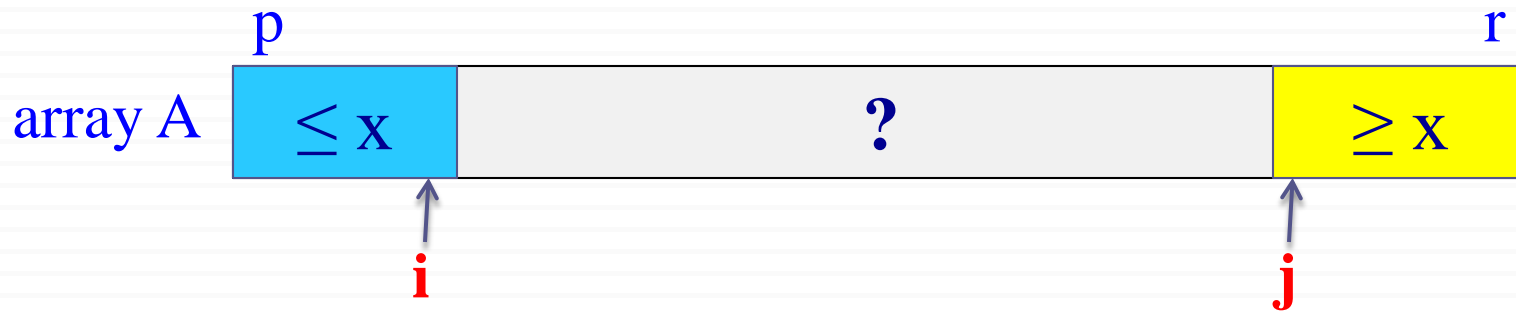
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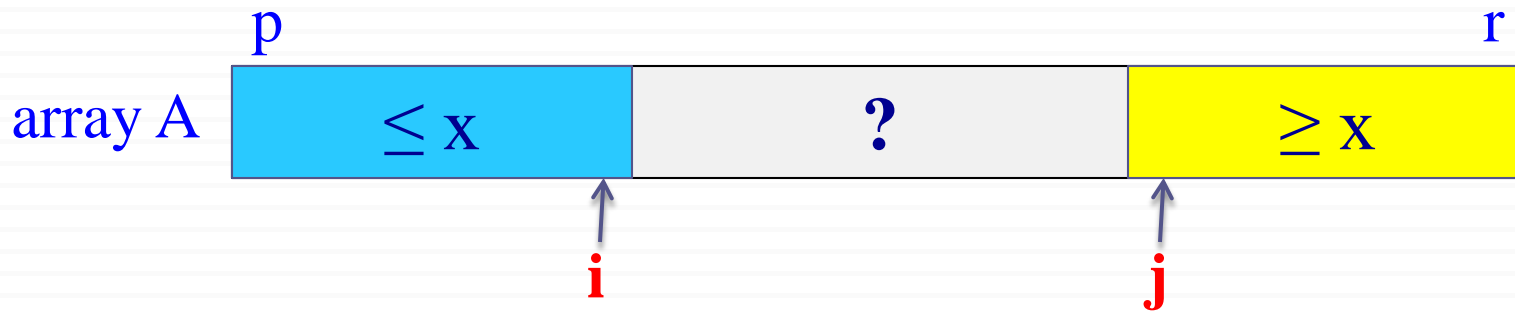
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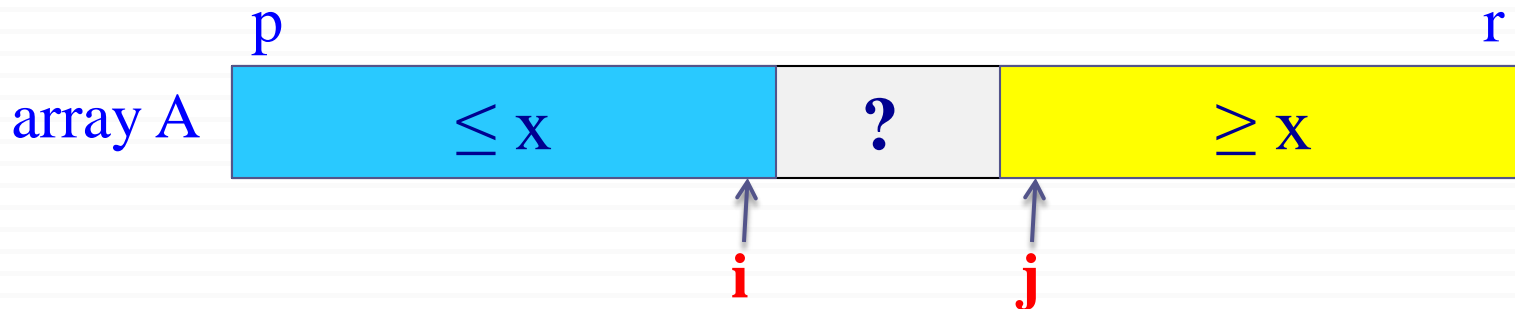
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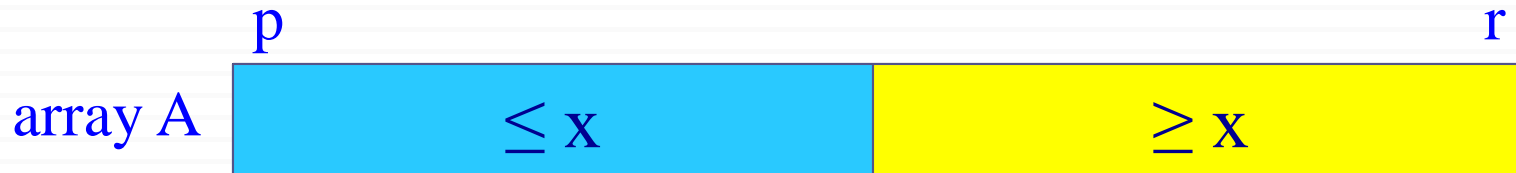
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# Hoare's Partitioning Algorithm

H-PARTITION ( $A, p, r$ )

$pivot \leftarrow A[p]$

$i \leftarrow p - 1$

$j \leftarrow r + 1$

**while true do**

**repeat**  $j \leftarrow j - 1$  **until**  $A[j] \leq pivot$

**repeat**  $i \leftarrow i + 1$  **until**  $A[i] \geq pivot$

**if**  $i < j$  **then** exchange  $A[i] \leftrightarrow A[j]$

**else return**  $j$



$pivot = 5$

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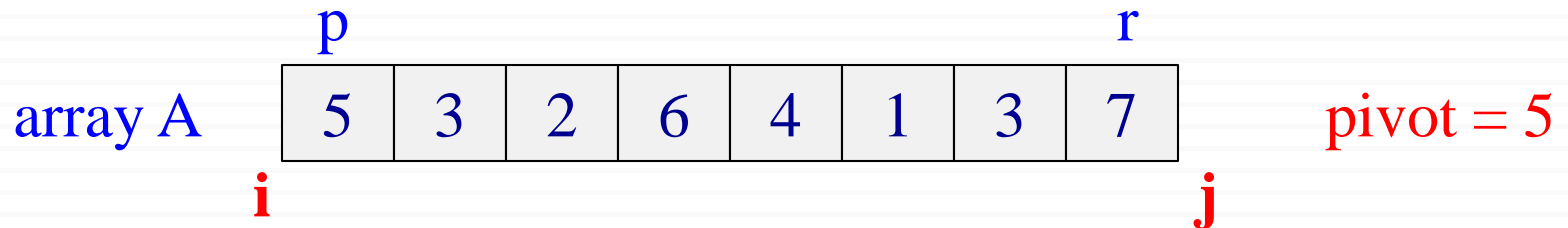
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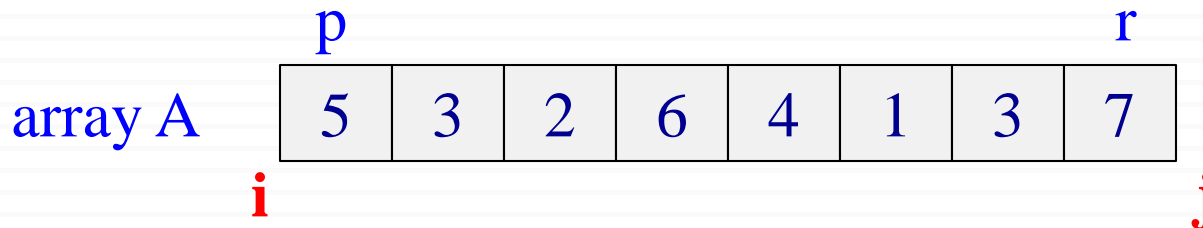
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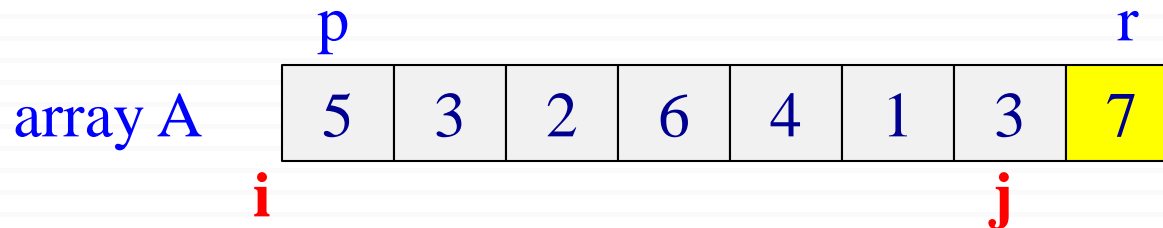
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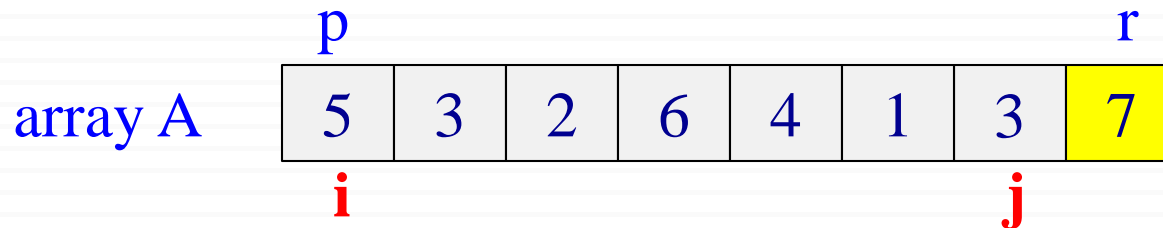
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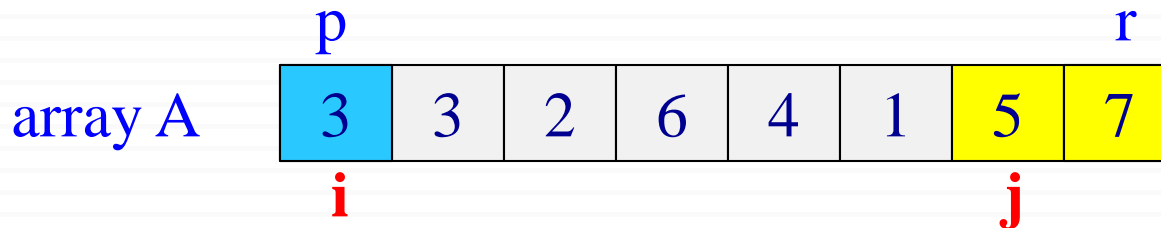
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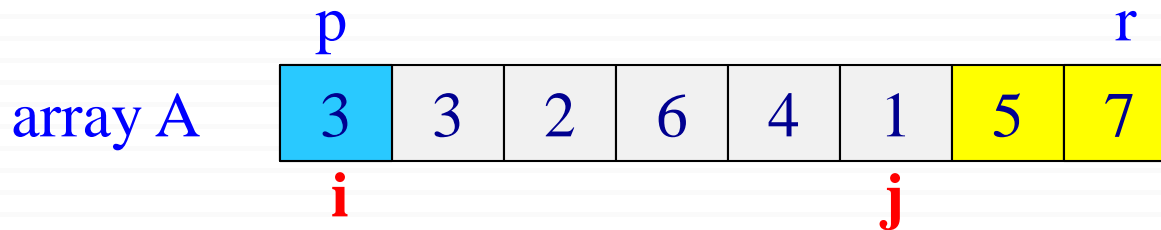
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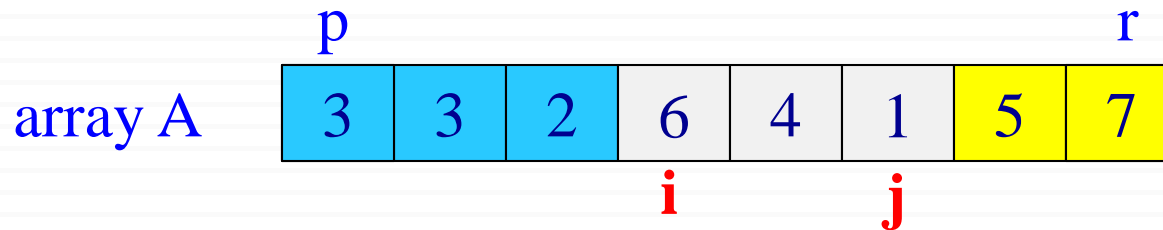
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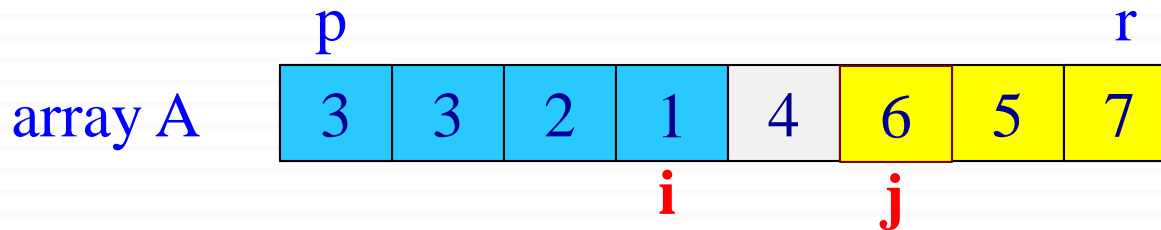
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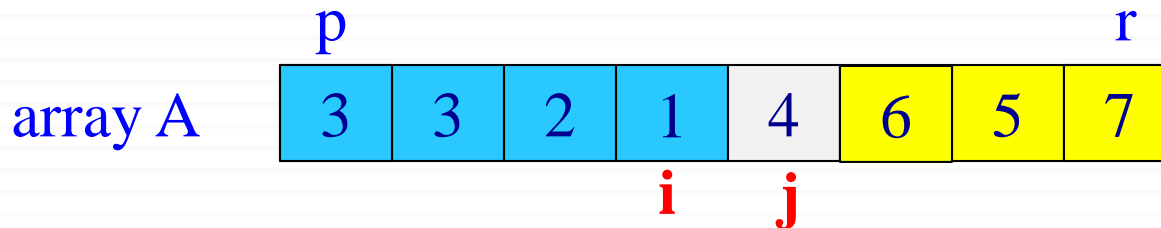
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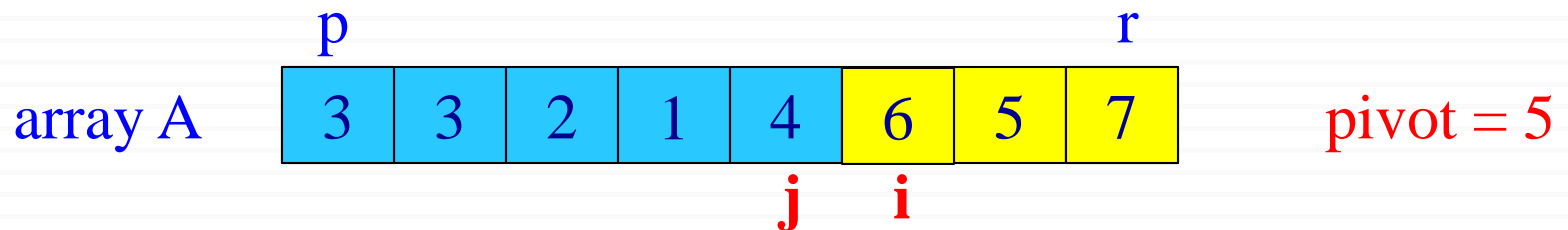
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# Hoare's Partitioning Algorithm - Notes

## H-PARTITION ( $A, p, r$ )

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**while true do**

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**if**  $i < j$  **then** exchange  $A[i] \leftrightarrow A[j]$

**else return**  $j$

Elements are exchanged when

- $A[i]$  is **too large** to belong to the **left** region
- $A[j]$  is **too small** to belong to the **right** region

assuming that the inequality is strict

The two regions  $A[p..i]$  and  $A[j..r]$  grow until  
 $A[i] \geq pivot \geq A[j]$



# Hoare's Partitioning Algorithm

H-PARTITION ( $A, p, r$ )

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**if**  $i < j$  **then** exchange  $A[i] \leftrightarrow A[j]$

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What is the asymptotic runtime of Hoare's partitioning algorithm?

$\Theta(n)$

QUICKSORT ( $A, p, r$ )

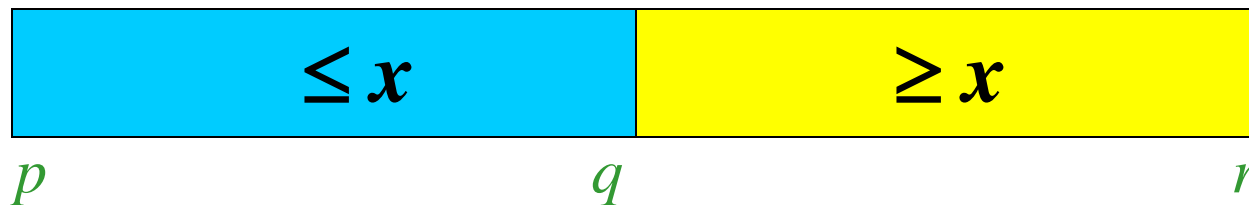
if  $p < r$  then

$q \leftarrow$  H-PARTITION( $A, p, r$ )

QUICKSORT( $A, p, q$ )

QUICKSORT( $A, q + 1, r$ )

Initial invocation: QUICKSORT( $A, 1, n$ )



# Question

H-PARTITION ( $A, p, r$ )

$pivot \leftarrow A[p]$

$i \leftarrow p - 1$

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**while true do**

**repeat**  $j \leftarrow j - 1$  **until**  $A[j] \leq pivot$

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QUICKSORT ( $A, p, r$ )




**if**  $p < r$  **then**

$q \leftarrow$  H-PARTITION( $A, p, r$ )

QUICKSORT( $A, p, q$ )

QUICKSORT( $A, q + 1, r$ )

**Q:** What happens if we select pivot to be  $A[r]$  instead of  $A[p]$  in **H-PARTITION**?

-  a) *QUICKSORT* will still work correctly.
-  b) *QUICKSORT* may return incorrect results for some inputs.
-  c) *QUICKSORT* may not terminate for some inputs.

# Hoare's Partitioning Algorithm: Pivot Selection

## H-PARTITION ( $A, p, r$ )

$pivot \leftarrow A[p]$

$i \leftarrow p - 1$

$j \leftarrow r + 1$

**while true do**

**repeat**  $j \leftarrow j - 1$  **until**  $A[j] \leq pivot$

**repeat**  $i \leftarrow i + 1$  **until**  $A[i] \geq pivot$

**if**  $i < j$  **then** exchange  $A[i] \leftrightarrow A[j]$

**else return**  $j$

If  $A[r]$  is chosen as the pivot:

Consider the example where  $A[r]$  is the largest element in the array:

5	3	6	4	3	7
---	---	---	---	---	---

End of H-PARTITION:  $i = j = r$

In QUICKSORT:  $q = r$

So, recursive call to:

**QUICKSORT** ( $A, p, q=r$ )  
**→ infinite loop**

## QUICKSORT ( $A, p, r$ )

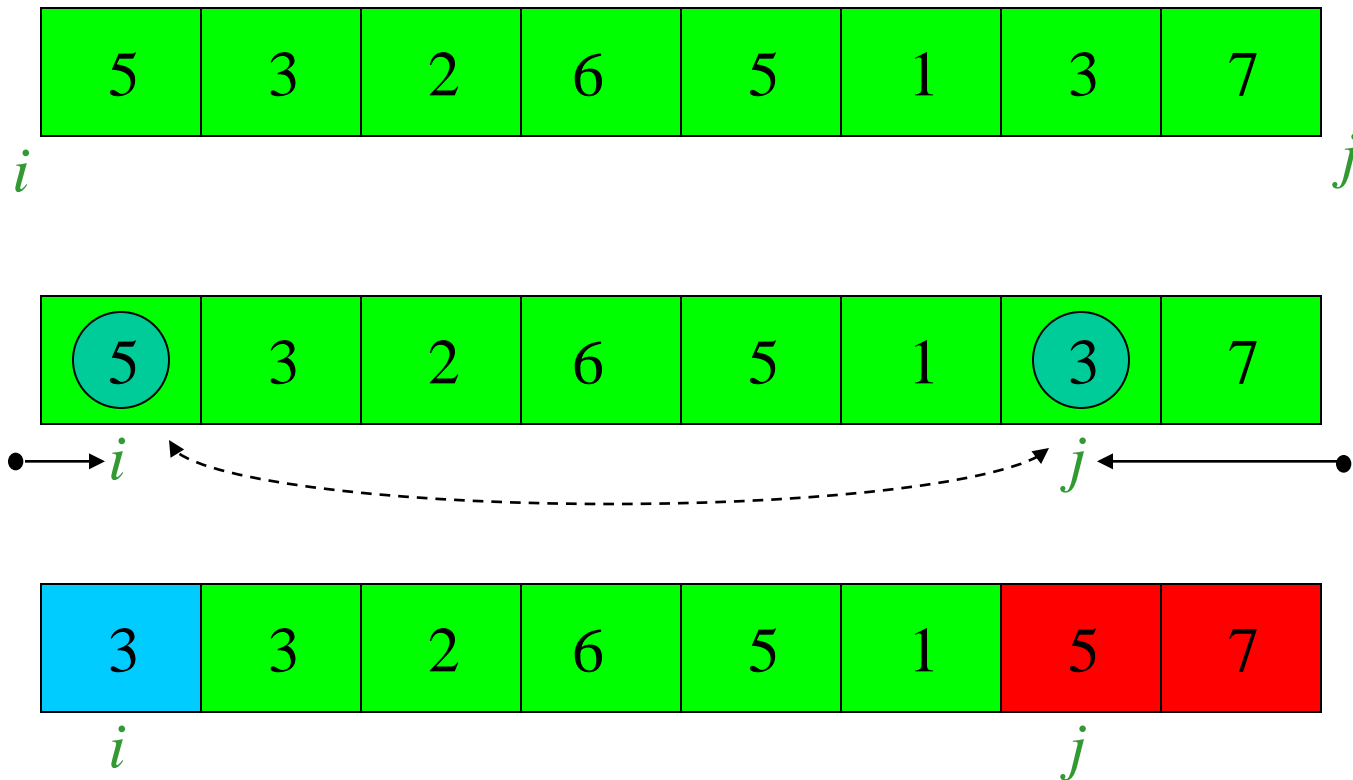
**if**  $p < r$  **then**

$q \leftarrow$  **H-PARTITION**( $A, p, r$ )

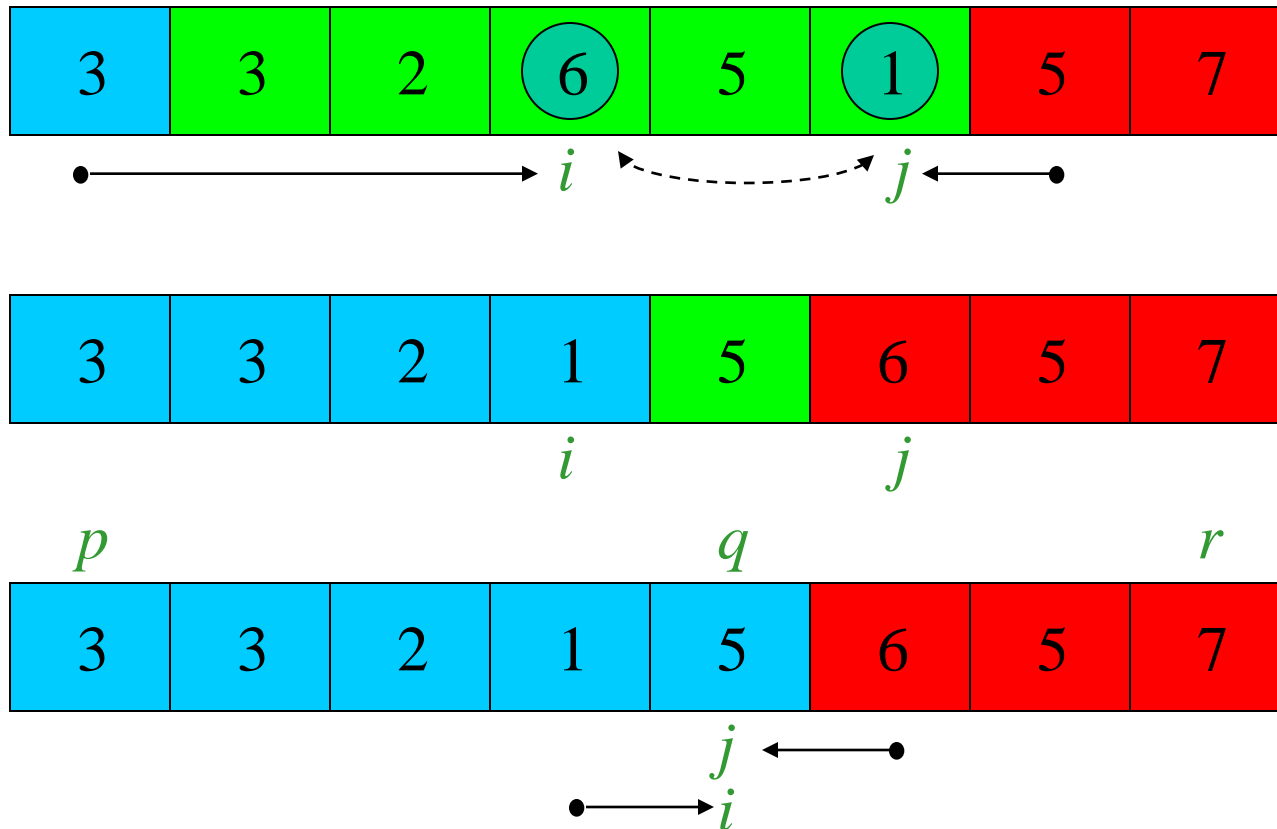
**QUICKSORT**( $A, p, q$ )

**QUICKSORT**( $A, q + 1, r$ )

# Hoare's Algorithm: Example 2 (pivot = 5)



## Hoare's Algorithm: Example 2 (pivot = 5)



Termination:  $i = j = 5$

# Correctness of Hoare's Algorithm

We need to prove 3 claims to show correctness:

- Indices  $i$  &  $j$  never reference  $A$  outside the interval  $A[p..r]$
- Split is always non-trivial; i.e.,  $j \neq r$  at termination
- Every element in  $A[p..j] \leq$  every element in  $A[j+1..r]$  at termination



# Correctness of Hoare's Algorithm

## Notations:

$k$ : # of times the while-loop iterates until termination

$i_m$ : the value of index  $i$  at the end of iteration  $m$

$j_m$ : the value of index  $j$  at the end of iteration  $m$

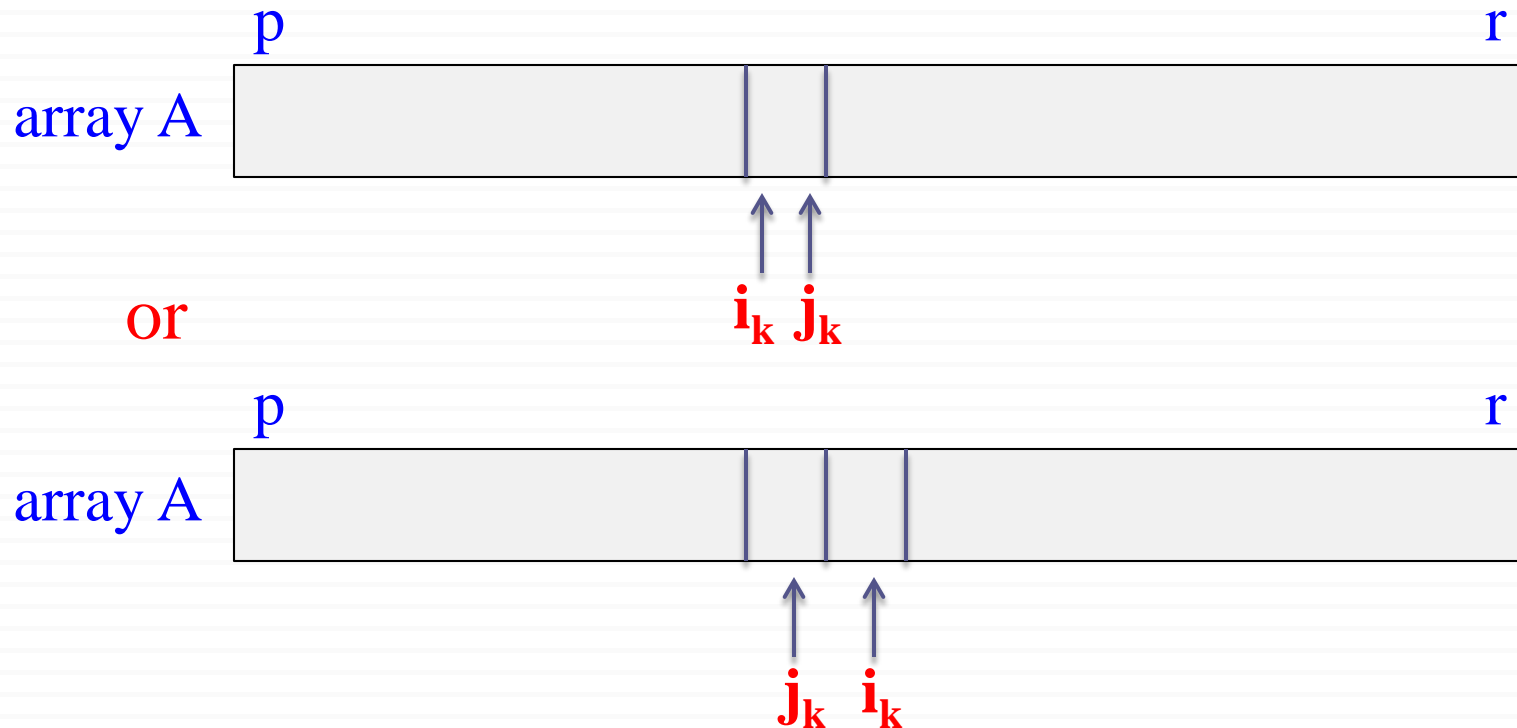
$x$ : the value of the pivot element

Note: We always have  $i_1 = p$  and  $p \leq j_1 \leq r$   
because  $x = A[p]$



# Correctness of Hoare's Algorithm

**Lemma 1:** Either  $i_k = j_k$  or  $i_k = j_k + 1$  at termination



# Correctness of Hoare's Algorithm

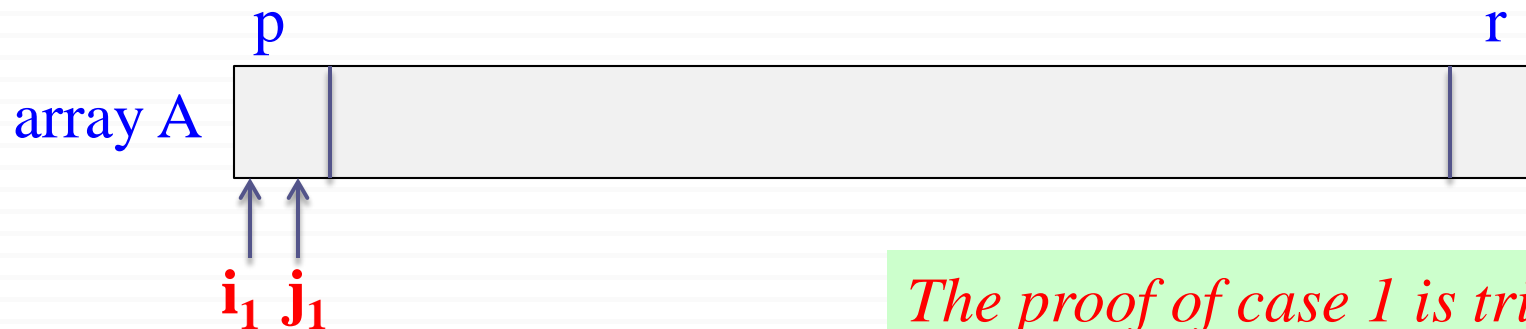
## Proof of Lemma 1:

The algorithm terminates when  $i \geq j$  (the else condition).

So, it is sufficient to prove that  $i_k - j_k \leq 1$

There are 2 cases to consider:

Case 1:  $k = 1$ , i.e. the algorithm terminates in a single iteration

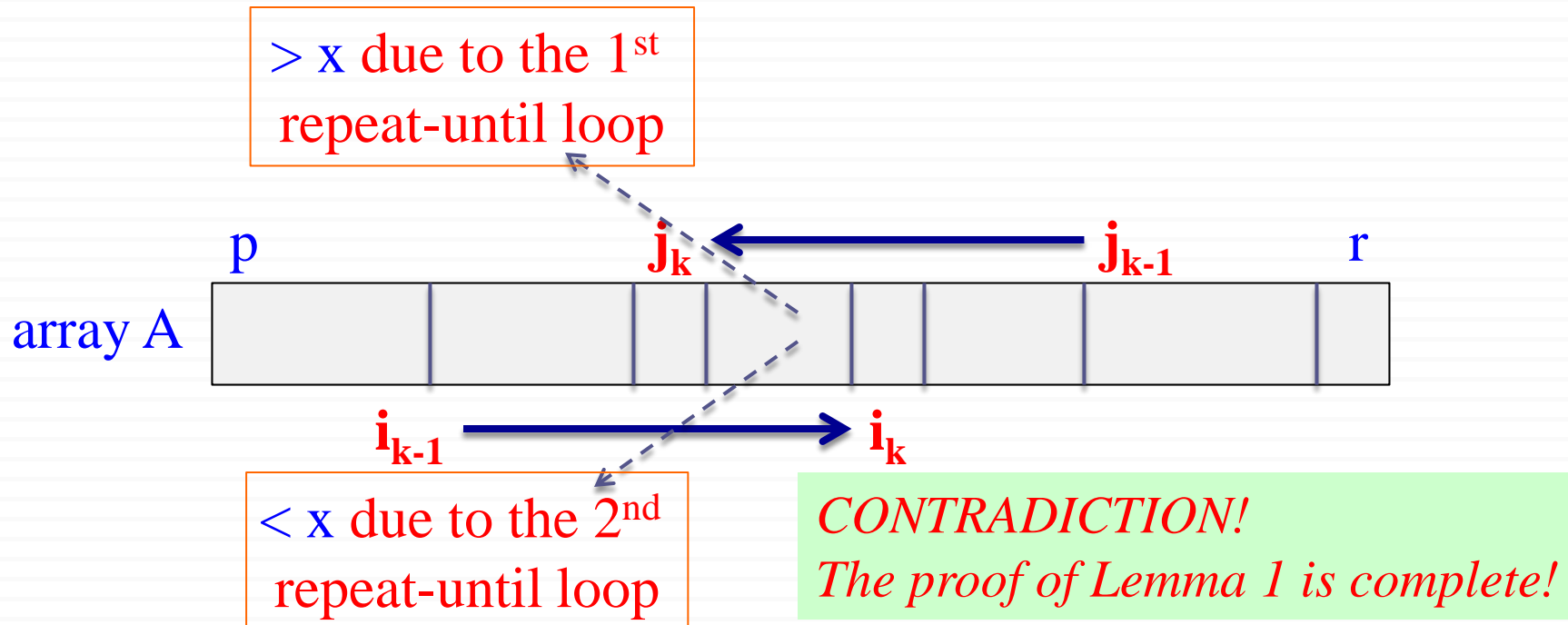


# Correctness of Hoare's Algorithm

## Proof of Lemma 1 (cont'd):

Case 2:  $k > 1$ , i.e. the alg. does not terminate in a single iter.

By contradiction, assume there is a run with  $i_k - j_k > 1$



# Correctness of Hoare's Algorithm

## Original correctness claims:

- (a) Indices  $i$  &  $j$  never reference  $A$  outside the interval  $A[p\dots r]$
- (b) Split is always non-trivial; i.e.,  $j \neq r$  at termination

## Proof:

For  $k = 1$ : Trivial because  $i_1 = j_1 = p$  (see *Case 1* in proof of *Lemma 2*)

For  $k > 1$ :

$i_k > p$  and  $j_k < r$  (due to the *repeat-until loops* moving indices)

$i_k \leq r$  and  $j_k \geq p$  (due to *Lemma 1* and the statement above)

→ The proof of claims (a) and (b) complete

# Correctness of Hoare's Algorithm

**Lemma 2:** At the end of iteration  $m$ , where  $m < k$  (i.e.  $m$  is not the last iteration), we must have:

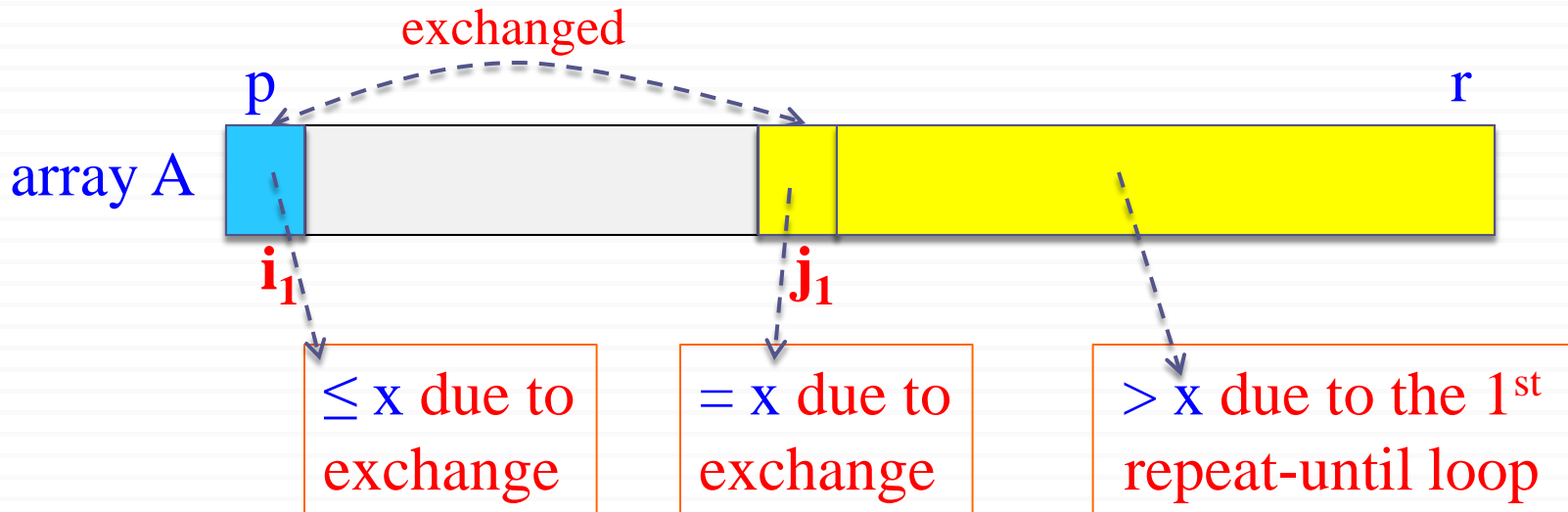
$$A[p..i_m] \leq x \quad \text{and} \quad A[j_m..r] \geq x$$



# Correctness of Hoare's Algorithm

## Proof of Lemma 2:

Base case:  $m=1$  and  $k > 1$  (i.e. the alg. does not terminate in the first iter.)



*Proof of base case complete!*

# Correctness of Hoare's Algorithm

## Proof of Lemma 2(cont'd):

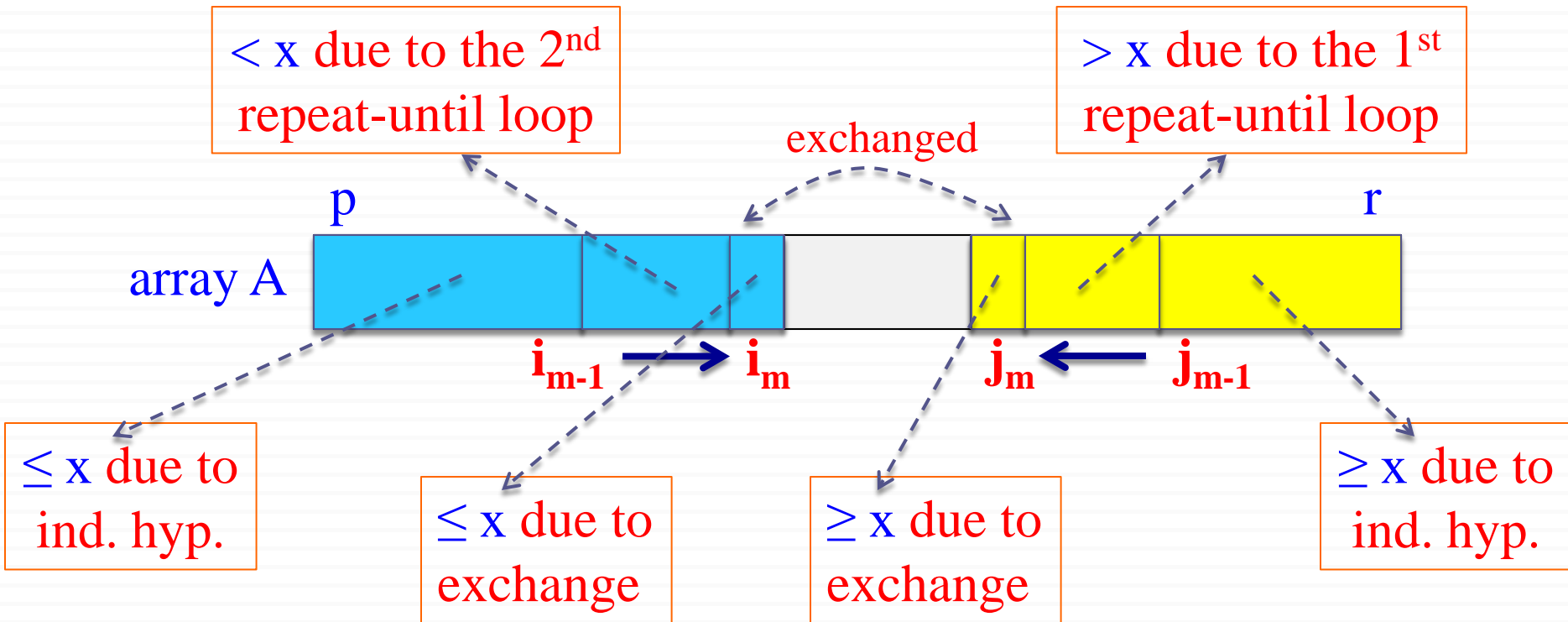
Inductive hypothesis: At the end of iteration  $m-1$ , where  $m < k$  (i.e.  $m$  is not the last iteration), we must have:

$$A[p..i_{m-1}] \leq x \quad \text{and} \quad A[j_{m-1} .. r] \geq x$$

General case: The lemma holds for  $m$ , where  $m < k$

# Correctness of Hoare's Algorithm

For  $1 < m < k$ , at the end of iteration  $m$ , we have:



*Proof of Lemma 2 complete!*



# Correctness of Hoare's Algorithm

## Original correctness claim:

(c) Every element in  $A[p..j] \leq$  every element in  $A[j+1..r]$  at termination

## Proof of claim (c)

There are 3 cases to consider:

Case 1:  $k = 1$ , i.e. the algorithm terminates in a single iteration

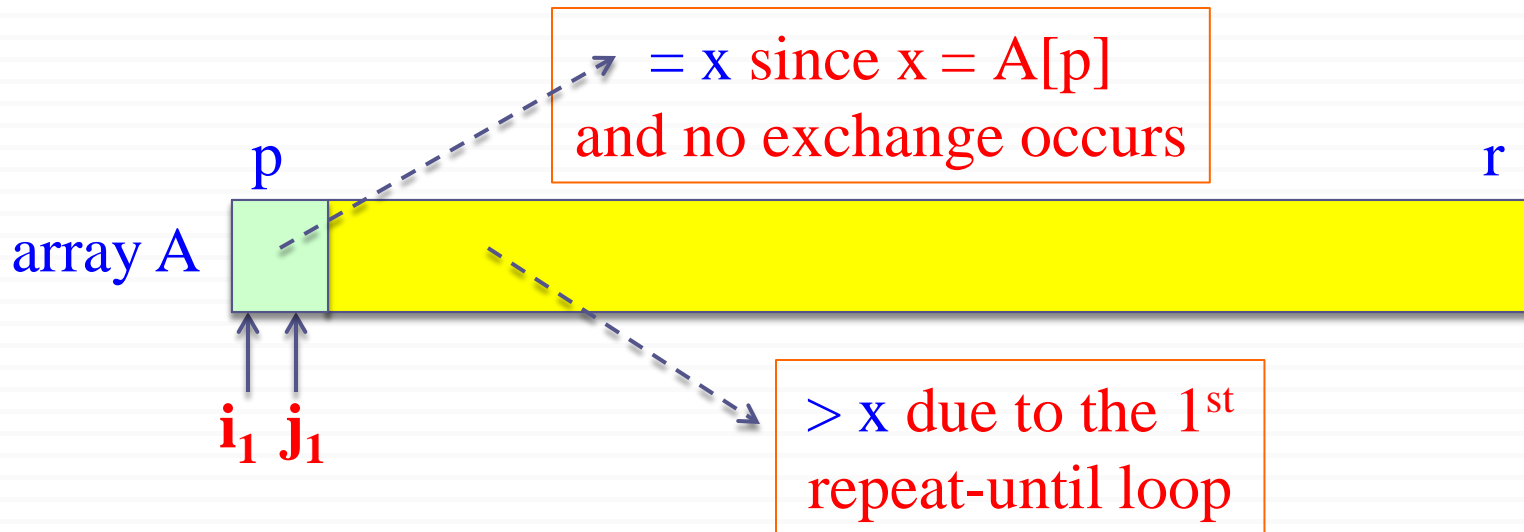
Case 2:  $k > 1$  and  $i_k = j_k$

Case 3:  $k > 1$  and  $i_k = j_k + 1$

# Correctness of Hoare's Algorithm

## Proof of claim (c):

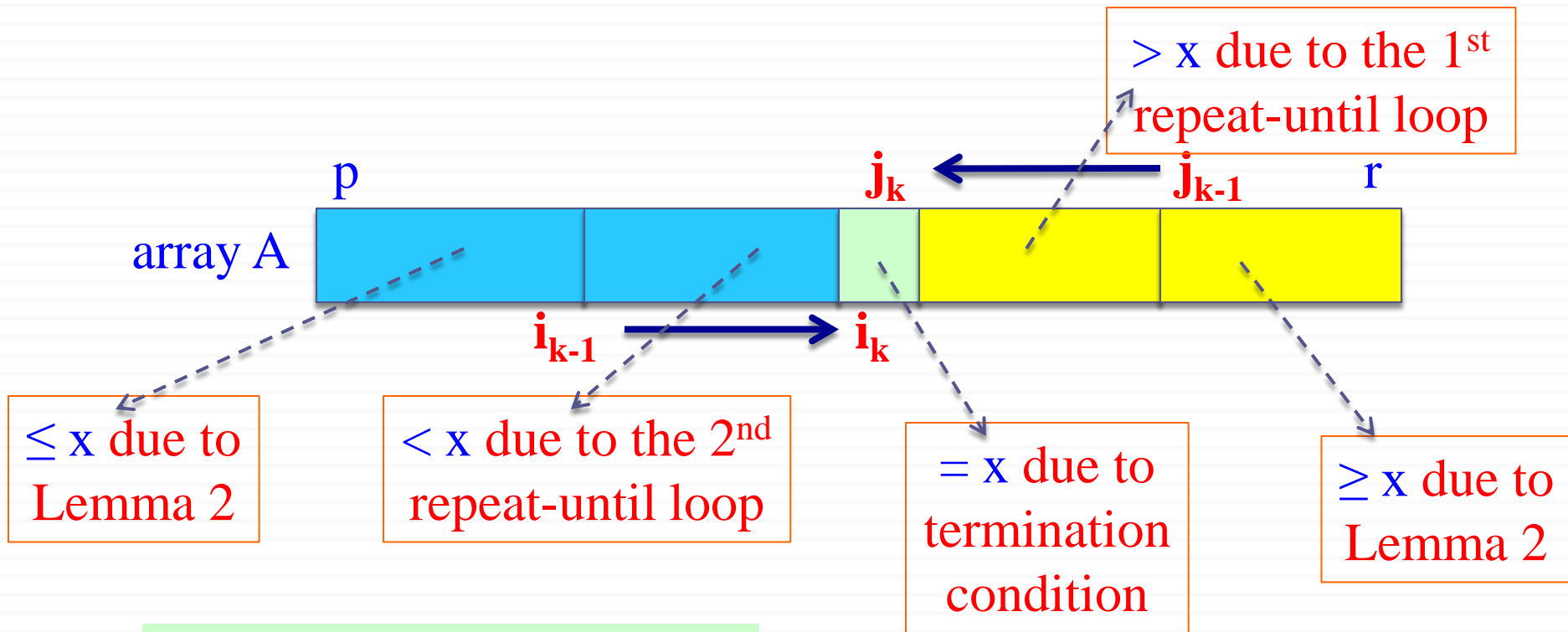
Case 1:  $k = 1$ , i.e. the algorithm terminates in a single iteration



*Proof of case 1 complete!*

# Correctness of Hoare's Algorithm

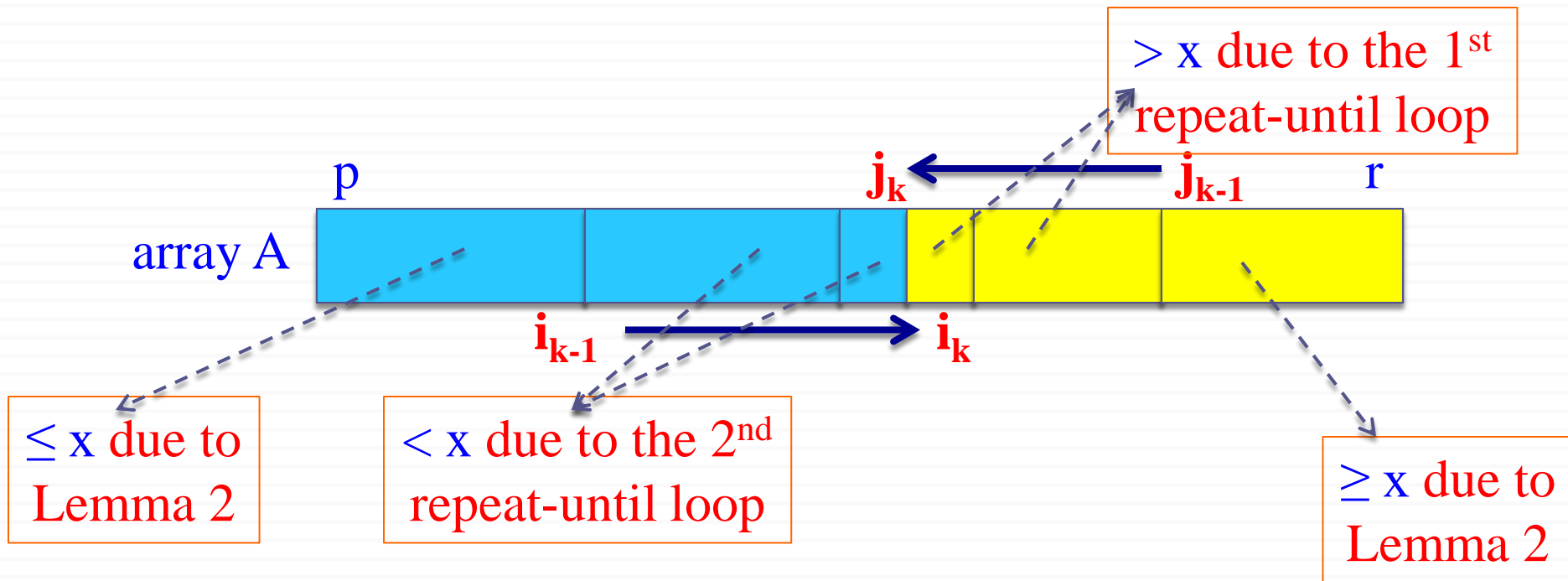
Proof of claim (c) (cont'd): Case 2:  $k > 1$  and  $i_k = j_k$



*Proof of Case 2 complete!*

# Correctness of Hoare's Algorithm

Proof of claim (c) (cont'd): Case 3:  $k > 1$  and  $i_k = j_k + 1$



*Proof of Case 3 complete!*

*Correctness proof complete!*

# Lomuto's Partitioning Algorithm

1. **Choose** a pivot element:  $\text{pivot} = x = A[r]$

2. **Grow** two regions:

from **left to right**:  $A[p..i]$

from **left to right**:  $A[i+1..j]$

such that:

every element in  $A[p..i] \leq \text{pivot}$

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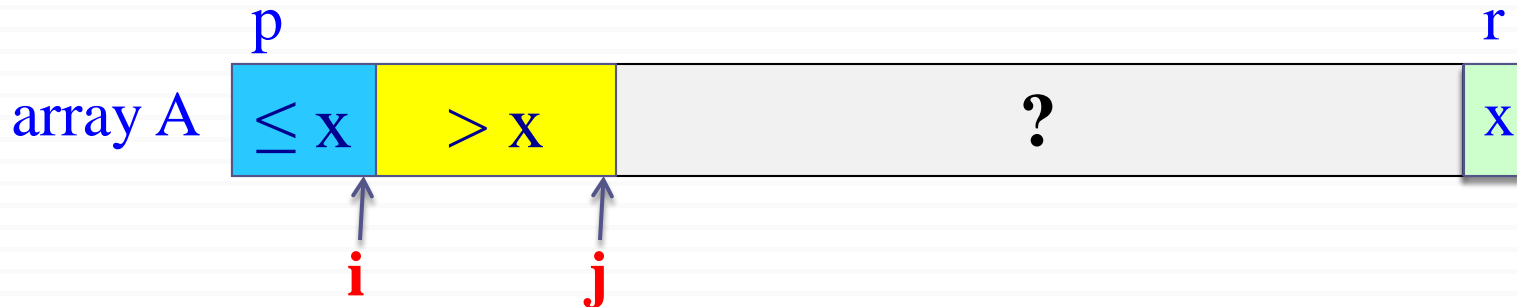
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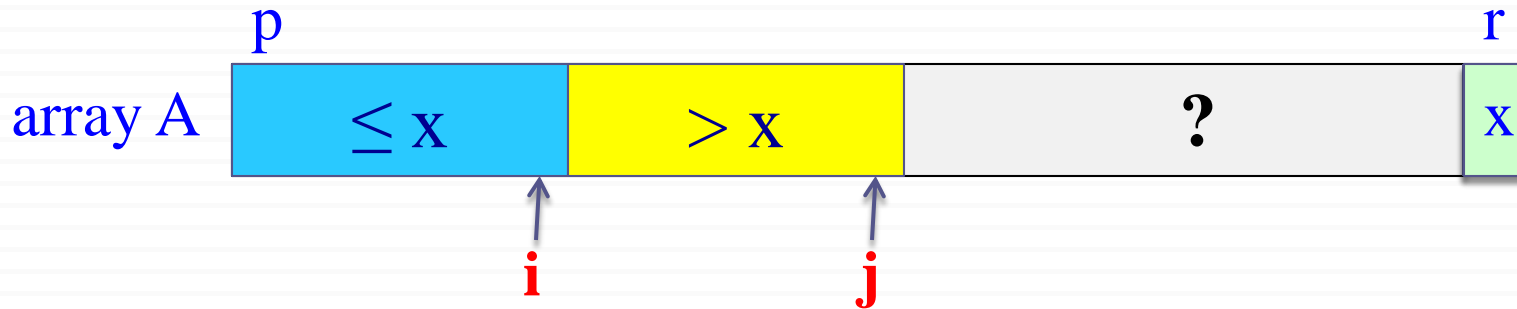
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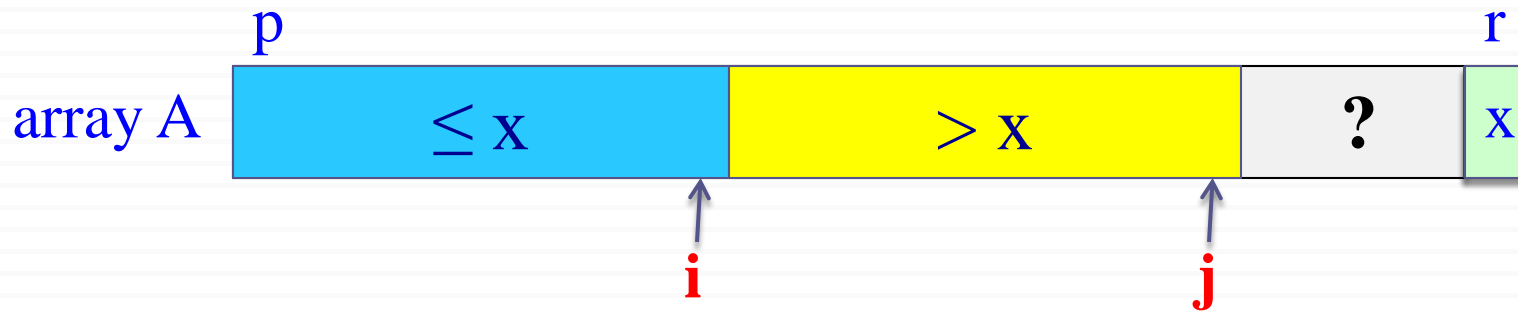
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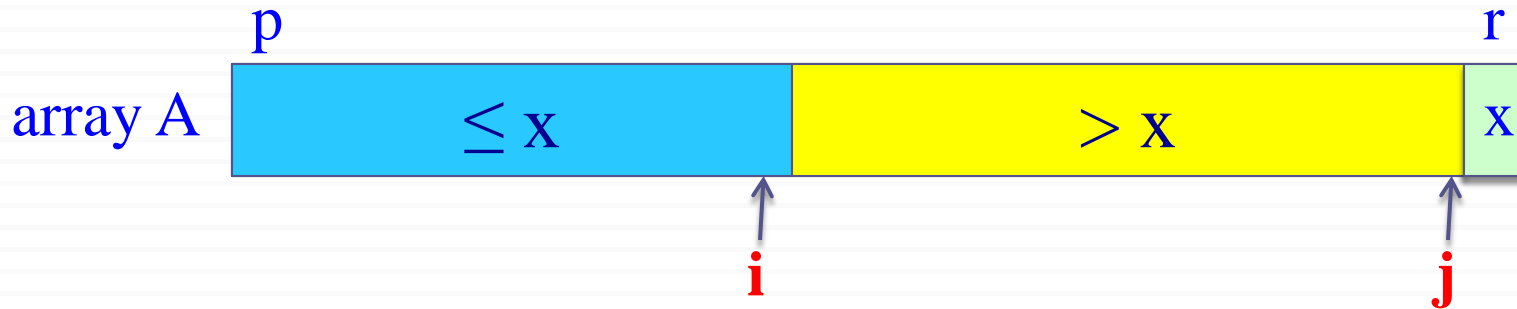
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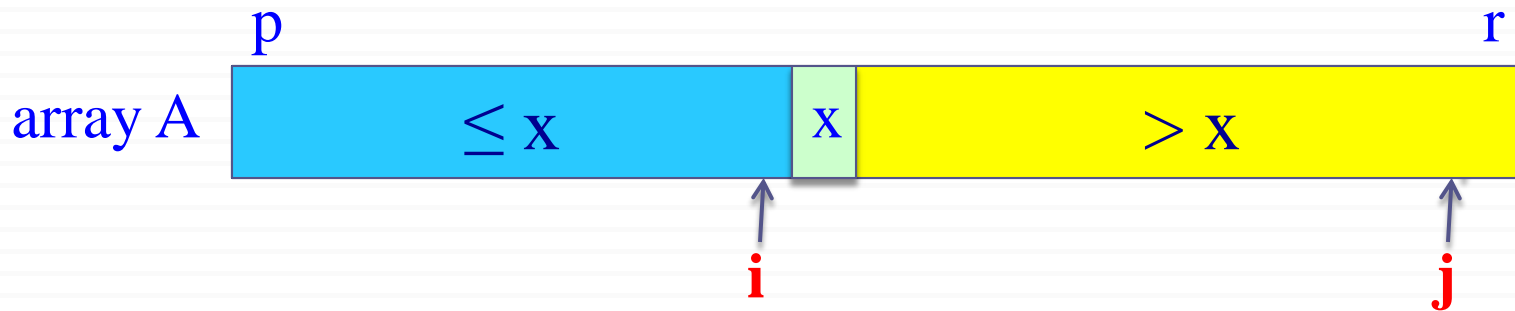
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# Lomuto's Partitioning Algorithm

## L-PARTITION ( $A, p, r$ )

$pivot \leftarrow A[r]$

$i \leftarrow p - 1$

**for**  $j \leftarrow p$  **to**  $r - 1$  **do**

**if**  $A[j] \leq pivot$  **then**

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**exchange**  $A[i] \leftrightarrow A[j]$

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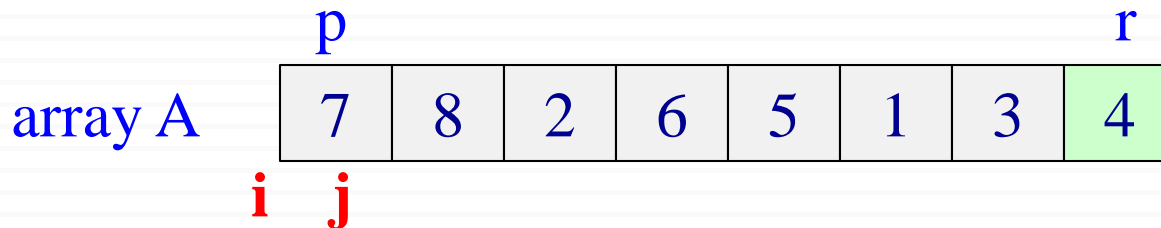
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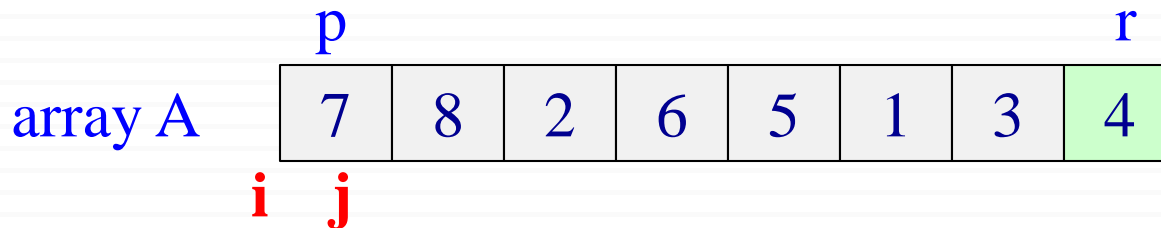
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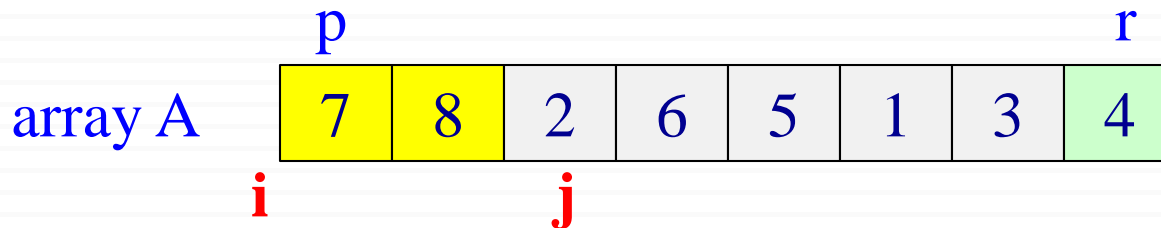
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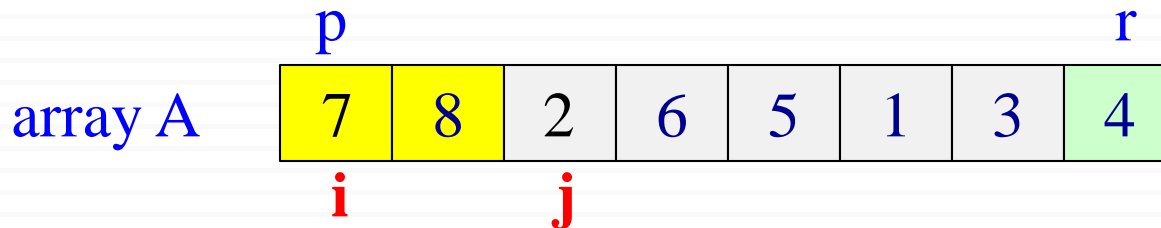
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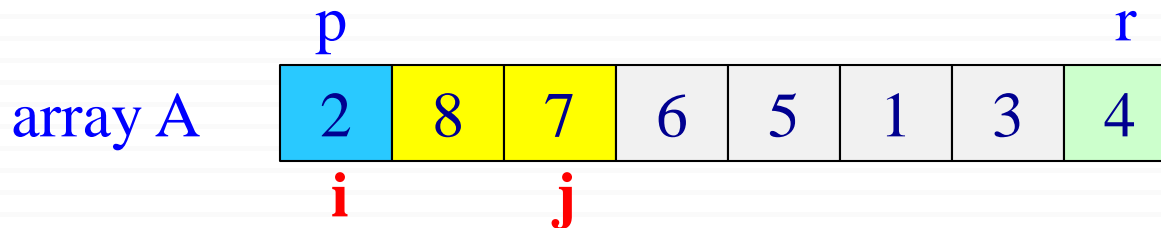
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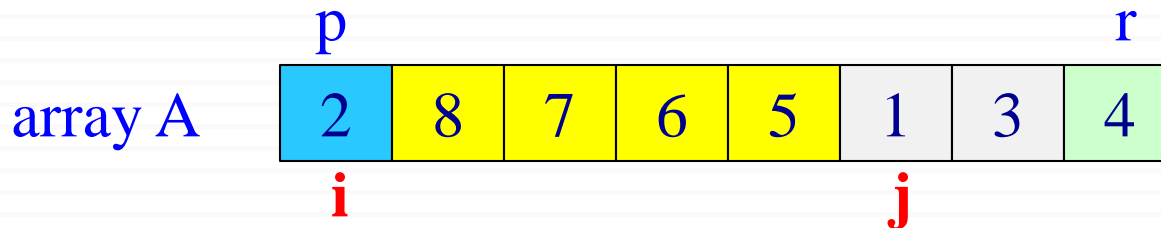
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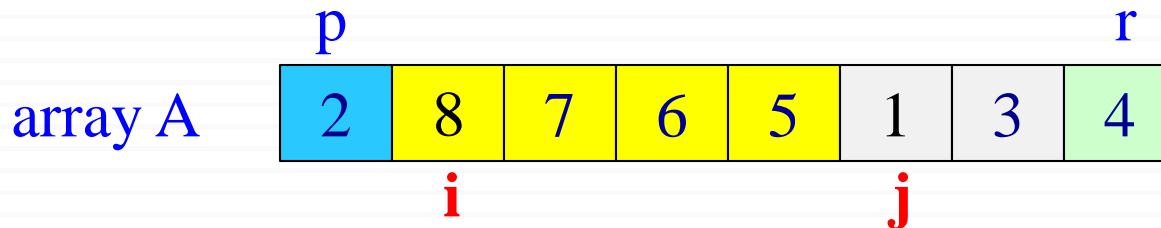
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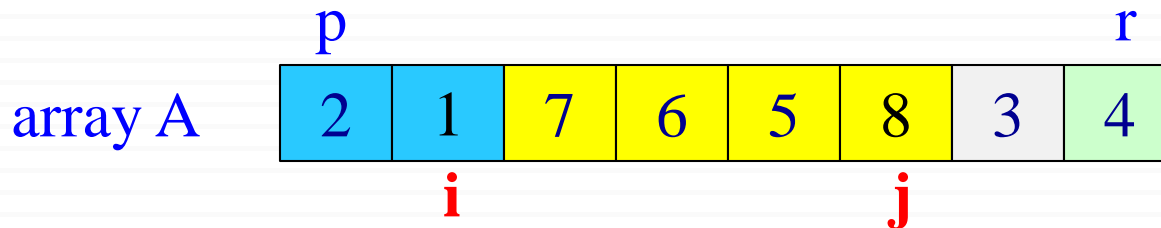
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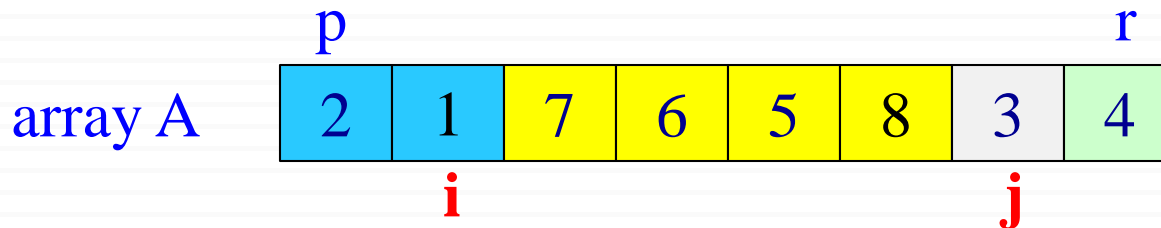
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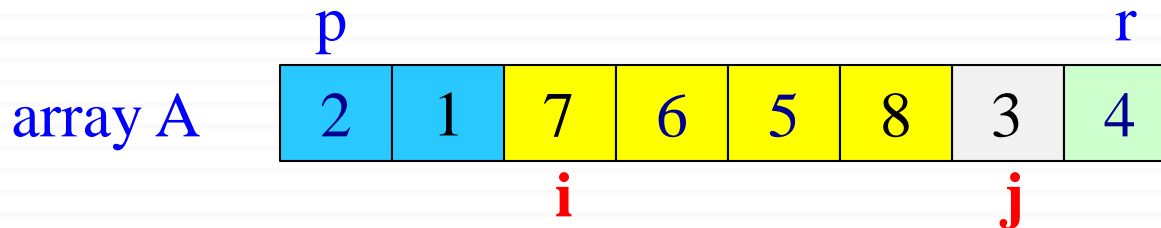
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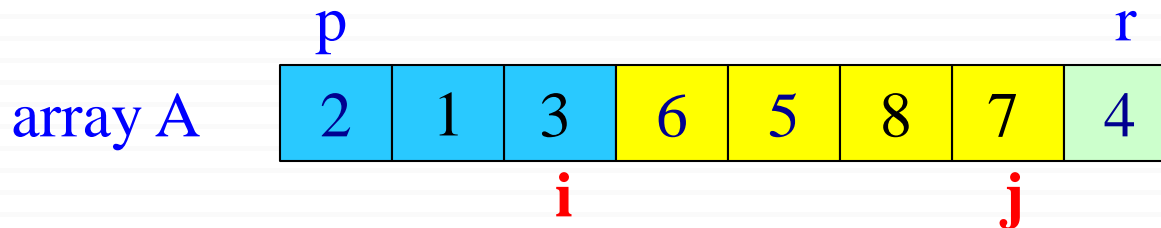
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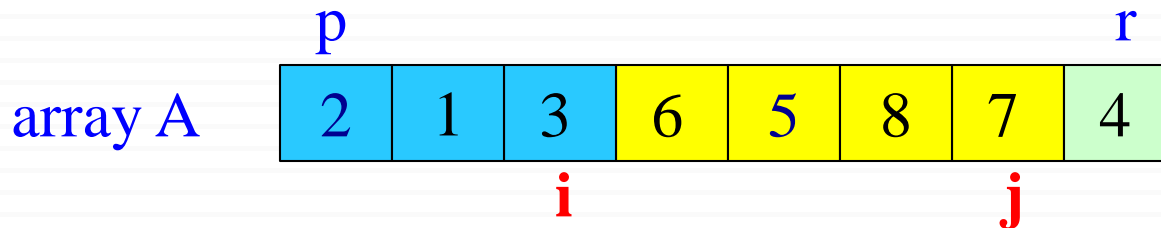
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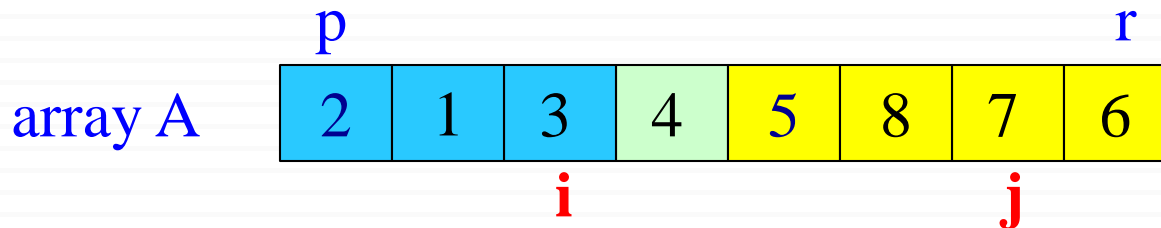
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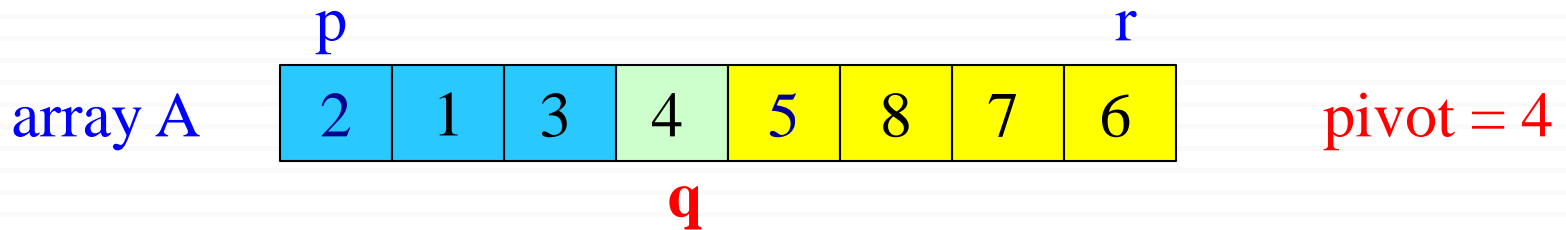
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What is the runtime of L-PARTITION?  $\Theta(n)$

**QUICKSORT** ( $A, p, r$ )

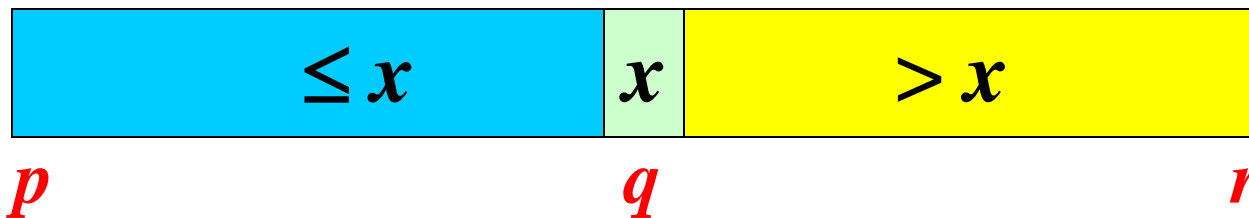
if  $p < r$  then

$q \leftarrow$  **L-PARTITION**( $A, p, r$ )

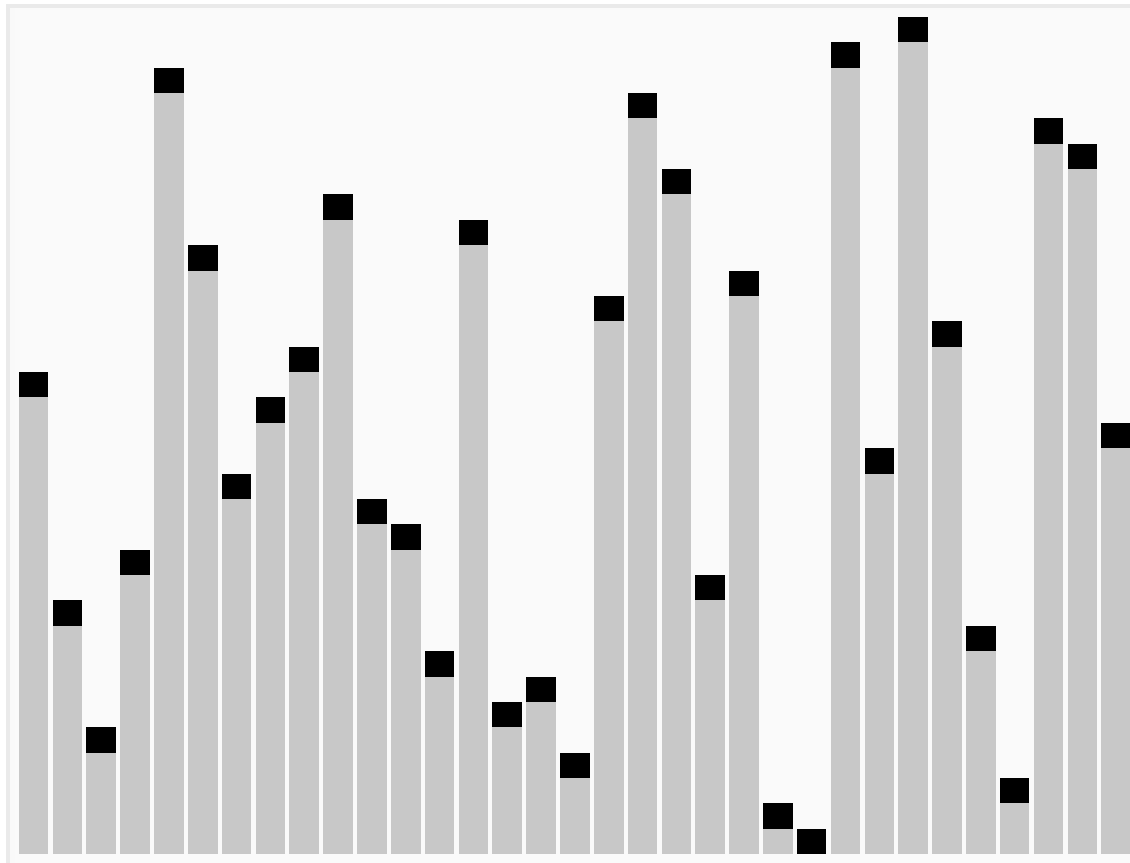
**QUICKSORT**( $A, p, q - 1$ )

**QUICKSORT**( $A, q + 1, r$ )

Initial invocation: **QUICKSORT**( $A, 1, n$ )



# Quicksort Animation



*from Wikimedia Commons*

# Comparison of Hoare's & Lomuto's Algorithms

**Notation:**  $n = r - p + 1$  &  $pivot = A[p]$  (Hoare)

&  $pivot = A[r]$  (Lomuto)

➤ # of element exchanges:  $e(n)$

- **Hoare:**  $0 \leq e(n) \leq \left\lfloor \frac{n}{2} \right\rfloor$ 
  - **Best:**  $k = 1$  with  $i_1 = j_1 = p$  (i.e.,  $A[p+1 \dots r] > pivot$ )
  - **Worst:**  $A[p+1 \dots p + \left\lfloor \frac{n}{2} \right\rfloor - 1] \geq pivot \geq A[p + \left\lfloor \frac{n}{2} \right\rfloor \dots r]$
- **Lomuto:**  $1 \leq e(n) \leq n$ 
  - **Best:**  $A[p \dots r - 1] > pivot$
  - **Worst:**  $A[p \dots r - 1] \leq pivot$

# Comparison of Hoare's & Lomuto's Algorithms

## ➤ # of element comparisons: $c_e(n)$

- Hoare:  $n + 1 \leq c_e(n) \leq n + 2$

- Best:  $i_k = j_k$

- Worst:  $i_k = j_k + 1$

- Lomuto:  $c_e(n) = n - 1$

## ➤ # of index comparisons: $c_i(n)$

- Hoare:  $1 \leq c_i(n) \leq \left\lfloor \frac{n}{2} \right\rfloor + 1$  ( $c_i(n) = e(n) + 1$ )

- Lomuto:  $c_i(n) = n - 1$

# Comparison of Hoare's & Lomuto's Algorithms

- # of index increment/decrement operations:  $a(n)$ 
  - **Hoare:**  $n + 1 \leq a(n) \leq n + 2$  ( $a(n) = c_e(n)$ )
  - **Lomuto:**  $n \leq a(n) \leq 2n - 1$  ( $a(n) = e(n) + (n - 1)$ )
- Hoare's algorithm is in general faster
- Hoare behaves better when pivot is repeated in  $A[p \dots r]$ 
  - **Hoare:** Evenly distributes them between left & right regions
  - **Lomuto:** Puts all of them to the left region